## IN THE CLAIMS:

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- 1. (Currently Amended) Method for checking the brake (22) of an electric motor (21), characterized in that in a measuring sequence in speed-regulated operation the brake (22) is applied for a short time and at least during this time a motor current  $(I_{des}, I_{act})$  is measured and on the basis of the measured data obtained in this way the brake torgue  $(M_{Br})$  of the brake (22) is determined.
- 2. (Currently Amended) Method according to claim 1, characterized in that the brake torque ( $M_{Br}$ ) is determined on the basis of the motor currents ( $I_1$ ,  $I_2$ ) with the brake (22) released and applied.
- 3. (Currently Amended) Method according to claim 1, characterized in that the brake (22) is applied for the time of at least one motor revolution.
- 4. (Original) Method according to claim 1, characterized in that brake application is repeated in a measuring sequence.
- 5. (Currently Amended) Method according to claim 1, characterized in that there is a reversal of the rotation direction of the motor (21) between brake applications or after groups of brake applications for the same rotation direction.

- 6. (Currently Amended) Method according to claim 1, characterized in that the measurement is performed during a movement of the motor (21), which is assisted by an optionally present gravitational moment.
- 7. (Currently Amended) Method according to claim 1, characterized in that the motor and/or brake temperature  $(T_{tr})$  is measured and used for correcting the determined brake torque  $(M_{tr})$ .
- 8. (Currently Amended) Method according to claim 1, characterized in that the measuring measured data (N<sub>act</sub>, I<sub>des</sub>, I<sub>act</sub>, T<sub>th</sub>/U<sub>br</sub>; M<sub>br</sub>) are recorded.
- 9. (Currently Amended) Method according to claim 1, characterized in that the measuring measured data (N<sub>acto</sub>-I<sub>des</sub>, I<sub>acto-Tob</sub>/U<sub>br</sub>; M<sub>br</sub>) are displayed.
- measuring measured data (N<sub>act</sub>, I<sub>des</sub>, I<sub>act</sub>, T<sub>th</sub>/U<sub>br</sub>; M<sub>br</sub>) are printed out.
- 11. (Currently Amended) Method according to claim 1, characterized in that the measuring measured data (N<sub>act</sub>, I<sub>des</sub>, I<sub>act</sub>, I<sub>th</sub>/U<sub>br</sub>; M<sub>tr</sub>) of different measuring sequences are automatically compared.